



# Alpha3D

Mobile mapping solution

### **Solution Description**

## Alpha3D

Dominant performance to make your work more mobile

CHC Navigation offers to geospatial professionals our premium high-performance, vehicle-independent mobile mapping solution to capture mass data in continuously changing world environments on dynamics, enabling them to get work done quickly and more accurately to increase their ROI.

The Alpha3D combines state-of-the-art high-performance hardware, such as long range, ultra-high speed, precise laser scanner, high-resolution HDR panoramic camera in combination with advanced GNSS receiver and high precision IMU, in one instrument with light weight and compact but in same time rugged design. All these features keep Alpha3D as one of most innovative system in market today.

## **Applications**



Roads & Highways



Rail & Infrastructure



**Tunnels** 



Digital city



Infrastructure utilities



Mining



Water



**Airports** 



**Public safety** 

### **Key Features**











#### High performance laser scanner

- Long range scanning up to 420m
- Extremely high-speed scanning of 1M points per second
- High point cloud density even on high speed driving
- · High quality of point cloud with low range noise

#### High resolution 360° image

- 30 MP HDR panoramic camera with superb image quality
- Fully calibrated point clouds and panorama images
- You can add additional imagery sensors to get extra information for application needs

#### Ready now, thinking about future

- Two RS232 ports for external device connection
- Ready to add 2nd scanner for more density of point cloud
- 2nd GNSS antenna to work on railway or water applications
- Easy-In easy-out SSD hard disc for raster data transfer

#### Capture and control data easily with CoCapture

- Manage the mission and automatically capture data
- BYOD, device free, any browser based operation
- WiFi or LAN cable connection
- Very simple and intuitive, user-friendly design

#### CoProcess software to manage scanning projects

- Intuitive user interface with rich functionality
- Semi-automated feature extractions
- Powerful engine can support massive data processing
- Easily export extracted information into CAD or GIS deliverables with our SW plugins



GPR, echo sounder or extra profiler.

## Whatever the task is, the Alpha3D is easily mounted on a variety of platforms, including different type of vehicles, trains, railway trolleys and boats, rapidly and efficiently collects the high density, accurate point clouds and powerful images data but also adds extra information from additional sensors, such as high-resolution camera, thermal camera,



## Get new revenue and increase ROI

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## **Specifications**

roof rack extension

General sys	stem pe	rforma	nce	
Number of laser	Single sc	anner hea	d system,	
scanners	future po	ssible to a	ıdd 2nd sca	nner
	head on a	additional	platform	
Typical horizontal accuracy	< 0.030 m	n RMS		
Typical vertical accuracy	< 0.025 m	n RMS		
Accuracy conditions	Without o	control po	ints,	
	open sky	condition	S	
Control unit	Internal n	nulti-core	industrial P	C,
	low powe	r consum	otion	
Field software	CoCaptu	re, browse	er-based, no	
	installatio	n require	d	
Control interface	BYOD (ar	ny tablet o	r laptop), V	ViFi
	or LAN ca	able conne	ection	
Data storage	Removab	le 2 TB SS	D hard disk	<
	with USB	3 interface	:	
3rd party hardware	1 x synch	ronization	port for 2n	d
synchronization	-	tenna2 x R	•	
	synchroni	zation po	rts (NMEA s	support)
Mounting			nt solution,	
		oad, rail a		
	water-bas	ed applic	ation	
Las	er scan	ner		
Laser class			th IEC 6082	5-1:201
Measuring principle				
	Time of flight measurement, echo signal digitization, online			
	-	processir		
Effective measurement rate(1)				1 MH <sub>2</sub>
Effective measurement rate <sup>(1)</sup> Maximum range, target			750 kHz	
Maximum range, target	300 kHz	500 kHz	750 kHz	
Maximum range, target reflectivity > 80% <sup>(2)</sup>	300 kHz 420 m	500 kHz 330 m	750 kHz 270 m	235 m
Maximum range, target reflectivity > 80% <sup>(2)</sup> Maximum range, target	300 kHz	500 kHz	750 kHz	
Maximum range, target reflectivity > 80% <sup>(2)</sup> Maximum range, target reflectivity > 10% <sup>(2)</sup>	300 kHz 420 m 150 m	500 kHz 330 m	750 kHz 270 m	235 m
Maximum range, target reflectivity > 80% <sup>(2)</sup> Maximum range, target reflectivity > 10% <sup>(2)</sup> Minimum range	300 kHz 420 m 150 m	500 kHz 330 m	750 kHz 270 m	235 m
Maximum range, target reflectivity > 80% <sup>(2)</sup> Maximum range, target reflectivity > 10% <sup>(2)</sup>	300 kHz 420 m 150 m 1.2 m 5 mm	500 kHz 330 m	750 kHz 270 m	235 m
Maximum range, target reflectivity > 80% <sup>(2)</sup> Maximum range, target reflectivity > 10% <sup>(2)</sup> Minimum range Accuracy <sup>(3)</sup> Precision <sup>(4)</sup>	300 kHz 420 m 150 m 1.2 m 5 mm 2 mm	500 kHz 330 m 120 m	750 kHz 270 m	235 m
Maximum range, target reflectivity > 80% <sup>(2)</sup> Maximum range, target reflectivity > 10% <sup>(2)</sup> Minimum range Accuracy <sup>(3)</sup>	300 kHz 420 m 150 m 1.2 m 5 mm 2 mm 360° "full	500 kHz 330 m 120 m	750 kHz 270 m 100 m	235 m
Maximum range, target reflectivity > 80% <sup>(2)</sup> Maximum range, target reflectivity > 10% <sup>(2)</sup> Minimum range Accuracy <sup>(3)</sup> Precision <sup>(4)</sup> Field of view Scan rate	300 kHz 420 m 150 m 1.2 m 5 mm 2 mm 360° "full Up to 1 0	500 kHz 330 m 120 m circle"	750 kHz 270 m 100 m	235 m
Maximum range, target reflectivity > 80% <sup>(2)</sup> Maximum range, target reflectivity > 10% <sup>(2)</sup> Minimum range Accuracy <sup>(3)</sup> Precision <sup>(4)</sup> Field of view Scan rate Scan speed (selectable)	300 kHz 420 m 150 m 1.2 m 5 mm 2 mm 360° "full Up to 1 0 Up to 250	500 kHz 330 m 120 m circle " 00 000 po ) scans/se	750 kHz 270 m 100 m	235 m
Maximum range, target reflectivity > 80% <sup>(2)</sup> Maximum range, target reflectivity > 10% <sup>(2)</sup> Minimum range Accuracy <sup>(3)</sup> Precision <sup>(4)</sup> Field of view Scan rate Scan speed (selectable)	300 kHz 420 m 150 m 1.2 m 5 mm 2 mm 360° "full Up to 1 0 Up to 250 Physical	500 kHz 330 m 120 m circle" 00 000 po ) scans/sec	750 kHz 270 m 100 m	235 m
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Maximum range, target reflectivity > 80% <sup>(2)</sup> Maximum range, target reflectivity > 10% <sup>(2)</sup> Minimum range Accuracy <sup>(3)</sup> Precision <sup>(4)</sup> Field of view Scan rate Scan speed (selectable)  Dimensions of instrument	300 kHz 420 m 150 m 1.2 m 5 mm 2 mm 360° "full Up to 1 0 Up to 250 Physical 51.3 × 31 20.08" ×	500 kHz 330 m 120 m circle" 00 000 po ) scans/sec	750 kHz 270 m 100 m	235 m
Maximum range, target reflectivity > 80% <sup>(2)</sup> Maximum range, target reflectivity > 10% <sup>(2)</sup> Minimum range Accuracy <sup>(3)</sup> Precision <sup>(4)</sup> Field of view Scan rate Scan speed (selectable)  Dimensions of instrument Weight of instrument	300 kHz 420 m 150 m 1.2 m 5 mm 2 mm 360° "full Up to 10 Up to 250 Physical 51.3 × 31 20.08" × 19.2 kg	500 kHz 330 m 120 m 120 m circle " 00 000 po ) scans/see × 67.2 cm 12.2" × 26	750 kHz 270 m 100 m	235 m
Maximum range, target reflectivity > 80% <sup>(2)</sup> Maximum range, target reflectivity > 10% <sup>(2)</sup> Minimum range Accuracy <sup>(3)</sup> Precision <sup>(4)</sup> Field of view Scan rate Scan speed (selectable)  Dimensions of instrument	300 kHz 420 m 150 m 1.2 m 5 mm 2 mm 360° "full Up to 1 0 Up to 250 Physical 51.3 × 31 20.08" × 19.2 kg 62.9 × 49	500 kHz 330 m 120 m circle" 00 000 po scans/sec	750 kHz 270 m 100 m 100 m	235 m
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Maximum range, target reflectivity > 80% <sup>(2)</sup> Maximum range, target reflectivity > 10% <sup>(2)</sup> Minimum range Accuracy <sup>(3)</sup> Precision <sup>(4)</sup> Field of view Scan rate Scan speed (selectable)  Dimensions of instrument Weight of instrument Dimensions of battery	300 kHz 420 m 150 m 1.2 m 5 mm 2 mm 360° "full Up to 1 0 Up to 250 Physical 51.3 × 31 20.08" × 19.2 kg 62.9 × 49 24.4" × 1 Up to 52	500 kHz 330 m 120 m 120 m circle " 00 000 po 0 scans/sec × 67.2 cm 12.2" × 26 .7 × 35.3 c 9.29" × 13 kg (depen	750 kHz 270 m 100 m 100 m	235 m 85 m
Maximum range, target reflectivity > 80% <sup>(2)</sup> Maximum range, target reflectivity > 10% <sup>(2)</sup> Minimum range Accuracy <sup>(3)</sup> Precision <sup>(4)</sup> Field of view Scan rate Scan speed (selectable)  Dimensions of instrument Weight of instrument Dimensions of battery  Weight of battery Dimensions of optional	300 kHz 420 m  150 m  1.2 m 5 mm 2 mm 360° "full Up to 1 0 Up to 250  Physical 51.3 × 31 20.08" × 19.2 kg 62.9 × 49 24.4" × 1 Up to 52 72 × 31 ×	500 kHz 330 m 120 m 120 m circle " 00 000 po 0 scans/see × 67.2 cm 12.2" × 26 .7 × 35.3 c 9.29" × 13 kg (depen 12 cm	750 kHz 270 m 100 m 100 m	235 m 85 m
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lmaging system		
Camera type	360° Spherical camera, additional adjustable	
	external cameras as option	
Number of cameras	6 sensors	
CCD size	2048 x 2448, 3.45 μm pixel size	
Lens	4.4 mm	
Resolution	30 MP (5 MP x 6 sensors), 10 FPS	
	JPEG compressed	
Coverage	90% of full sphere	
High Dynamic Range (HDR)	Cycle 4 gain and exposure presets	
Positioning	g and orientation system	
GNSS system	Multiple GPS, GLONASS, Galileo, BeiDou, SBAS and QZSS constellation, L-Band, single and dual antenna support	
IMU update rate	Standard 200 Hz (user selectable 1 to 1000 Hz)	
Gyro bias	≤0.1 deg/hr, 1σ (max)	
instability (25°C)	≤0.05 deg/hr, 1σ (typical)	
Gyro bias offset (25°C)	±2 deg/hr	
Gyro scale factor	≤200 ppm, 1σ	
Gyro range	±490 deg/sec	
Angle Random Walk	≤0.012 deg/√hr	
Accelerometer range	±10 g	
Accelerometer bias	<0.05 mg	
Accelerometer scale factor	250 ppm/°C, 1σ (max), ≤100 ppm/°C, 1σ (typical)	
Position accuracy NO GNSS outage	0.010 m RMS horizontal, 0.020 m RMS vertical, 0.005 degrees RMS pitch/roll, 0.017 degrees RMS heading	
Wheel sensor (DMI)	Yes, optional	
Environmental		
Operating temperature	-10 °C to +40 °C	
Storage temperature	-20 °C to +50 °C	
IP rating	IP64	
Humidity (operating)	80%, non-condensing	
Maximum vehicle speed	110 km/h (68 mph)	
for data acquisition		
Humidity (operating)	80%, non-condensing	
	Electrical	
Battery type	External battery in protected case, also	
	support direct vehicle power source	
Input voltage	24 V DC	
Power consumption	Typ. 240 W	
Operating time	Up to 8 hrs	
(1) Rounded values, selectable by measurement program. (2) Typical values for average conditions. (3) Accuracy is the degree of conformity of a measured quantity to its actual (true) value.		

- (4) Precision is the degree of conformity of a measured quantity to its actual (true) value (4) Precision is the degree to which further measurements show the same results.

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Shanghai Huace Navigation Technology Ltd.

599 Gaojing Road, Building D Shanghai, 201702, China

+86 21 54260273 WWW.CHCNAV.COM









<sup>\*</sup>Specifications are subject to change without notice.